# Quick start guide

# Power on/off

long-press the power button for 3s.



# Charging

connect to the charger immediately when the power is lower than 10%.



## Delivery

On the Delivery mode page, click the corresponding table to start.

Delivery mode		A组	B组 C组	÷ () ا	12%
	A1	A2	A3	A4	1
	B1	B2	B3	B4	
	C1	C2	C3	C4	•
	C5	C6	C7	C8	•
	D1	D2	D3	D4	
		Start!			Test

## Cruise

On the Cruise mode page, select the cruise route and click Start.

Cruise mode	11%
<ul> <li>Stay location settings</li> </ul>	Select route
	1
	2
	3
	Start!
Pause location during cruise	

#### Pause

During the PuduBot executes the task, anywhere on the screen can be clicked to pause it.



#### Setting

Click the menu bar on the upper left corner to enter the settings page, where many functions can be set, such as WIFI, volume, speed, etc.

= Setting		<b>a</b> 1 🕈 🗆 11%
Basic settings	English	· ·
÷ WLAN	<b>中文</b>	
🗊 Map settings		
Volume settings	한국어	
Voice settings	中文(繁體)	
Speed settings	日本語	
📃 Traysettings		

#### Note

1. Press the emergency stop switch on the top of the robot to make it stop immediately. Then it cannot run and the switch needs to be rotated to make it move;

2. Do not to deliver liquid dishes, such as soup or hot pot, which may spill on the trays and cause other accidents;

3. The robot has an automatic obstacle avoidance function, but it is strictly forbidden to block the robot suddenly during its running. Otherwise, it may cause an accident;

4. The lidar, RGBD and Marker camera are strictly prohibited from being blocked by any objects;

5. Please designate a person to charge the robot, don't charge it unattended;

6. Please keep the robot and charge position in a dry storage location and at room temperature. Forbidden to place the robot and charger in a high-temperature area for charging (>40°C) and let water in.